# SCC Inc.

# **Installation Instructions**

# Document No. DR-1100 April 4, 2022

# **DR Series**

# DR... Variable Frequency Drives (VFD's)



## **Product Description**

DR... series VFDs precisely control the speed of an AC induction motor. They come preprogrammed for each application to simplify installation.

## **Optional Accessories**

In addition to the VFD, the following optional components may be ordered with the drive:

- NEMA 1 Kit
- Braking Resistor
- Braking Unit
- Line Reactor
- Load Reactor

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## **Recommended Installation Tools**

The following tools are recommended for installing the drives:

- Drill
- Drill bit (See DR-1000 for mounting dimensions)
- #2 Phillips screwdriver
- Flathead screwdriver (Sizes Required: 3mm, 6mm)
- Pencil
- Wire strippers
- Wire cutters
- Wire crimpers
- Hacksaw (for Conduit)
- Masking Tape
- Round File
- ¼" or ¾" Drive Metric Socket Set (larger drives use up to 17mm)

#### **Recommended Installation Consumables**

- Conduit and conduit fittings (½", ¾", 1", or larger size depending on wire size)
- Wires (See Table 2 for wire gauge recommendation)
- Mounting Fasteners
- Crimp-on fittings (optional)

#### **Mounting Notes**

#### Installation Inside an Electrical Enclosure

When installing a drive in an electrical enclosure, mount the drive vertically. A DR-...B can be mounted horizontally but requires an external fan mounted in the panel to ensure sufficient airflow to the drive.

#### **Stand-Alone Installation:**

When installing a drive stand-alone (not in an electrical enclosure) the drive must be installed vertically and typically a NEMA 1 kit is required by local electrical codes. The NEMA 1 kit allows the installer to attach conduit directly to the drive. See Document DR-1000 for a complete listing of NEMA 1 kit part numbers.

The NEMA 1 kits vary in size between drives and come in different variations. Installation instructions are below for all configurations.

## DRN1-Bx-x NEMA 1 Procedure A Kit Install

Compatible with DR...B (GA500) drives under 10HP:

DR-240F16-1B, DR-240F14-1B, DR-240F34-1B, DR-240001-1B, DR-240002-1B, DR-240003-1B, DR-240005-1B, DR-240F16-3B, DR-240F14-3B, DR-240F34-3B, DR-240001-3B, DR-240002-3B, DR-240003-3B, DR-240005-3B, DR-240005-3B, DR-240007-3B, DR-480007-3B, DR

#### **Components Supplied**

Figure 1 shows the components supplied with the DRN1-Bx-x NEMA 1 kit:



Figure 1: Pieces Supplied with the Procedure A DRN1-Bx-x NEMA 1 Kit

1. Base

- 4. (2) Pan head screws
- 5. (2) C-
- Front cover
   Top cover
- 5. (2) C-washers6. M4 x 10 mounting truss head screw

# Installation

1. To install the top cover, insert the hooks on the rear side of the top cover into the drive placement holes as shown below. Then push the top cover into place.



Figure 2: Installing the Top Cover (Procedure A DRN1-Bx-x)

## DRN1-Bx-x NEMA 1 Procedure A Kit Install (continued)

2. Remove the knock-out holes on the base before installing. This can be done by putting the end of a flathead screwdriver into the center hole and moving up and down. Then file the rough surface to smooth the edges.



Figure 3: Removing Knock-Out Holes (Procedure A DRN1-Bx-x)

3. Remove the drive ground terminal screws



A - Screws

Figure 4: Removing Ground Terminal Screws (Procedure A DRN1-Bx-x)

4. Align the base holes with the ground screw holes on the drive. Using the supplied screws, tighten the screws.



Figure 5: Installing the Base (Procedure A DRN1-Bx-x)

## DRN1-Bx-x NEMA 1 Procedure A Kit Install (continued)

5. Using the (2) C-Washers and pan head screws, connect one or two ground wires to the base.



Figure 6: Ground Wiring and Screws (Procedure A DRN1-Bx-x)

6. The front cover will slide over the front face of the base and lock into place with the mounting truss head screw. For higher horsepower drives, the cover may have hooks that clip into the drive. If so, refer to the second image below. Insert the clips into the positions shown, then slide down to lock into place and install the mounting truss head screw.



Figure 7: Installing the Front Cover (Procedure A DRN1-Bx-x)

#### DRN1-Bx-x NEMA 1 Procedure B Kit Install

Compatible with DR...B (GA500) drives 10HP and over:

DR-240015-3B, DR-240020-3B, DR-240025-3B, DR-240030-3B, DR-480010-3B, DR-480015-3B, DR-480020-3B, DR-480020-3B, DR-480020-3B, DR-480040-3B

#### **Components Supplied**

Figure 1 shows the components supplied with the DRN1-Bx-x NEMA 1 kit:



Figure 8: Pieces Supplied with the Procedure B DRN1-Bx-x NEMA 1 Kit

1. Base

- 4. (2) Pan head screws
- 2. Front cover
- 3. Top cover
- 5. (2) Mounting Screw

### Installation

1. To install the top cover, insert the hooks on the rear side of the top cover into the drive placement holes as shown below. The top cover has a single arrow to point towards the front of the drive.



Figure 9: Installing the Top Cover (Procedure B DRN1-Bx-x)

## DRN1-Bx-x NEMA 1 Procedure B Kit Install (continued)

2. Remove the knock-out holes on the base before installing. This can be done by putting the end of a flathead screwdriver into the center hole and moving up and down. Then file the rough surface to smooth the edges.



Figure 10: Removing Knock-Out Holes (Procedure B DRN1-Bx-x)

3. Remove the drive ground terminal screws



A - Screws



4. Align the base holes with the ground screw holes on the drive. Using the supplied screws, tighten the screws.

# DRN1-Bx-x NEMA 1 Procedure B Kit Install (continued)



Figure 12: Installing the Base (Procedure B DRN1-Bx-x)

5. Using the (2) C-Washers and pan head screws, connect one or two ground wires to the base.



Figure 13: Ground Wiring and Screws (Procedure B DRN1-Bx-x)

## DRN1-Bx-x NEMA 1 Procedure B Kit Install (continued)

6. The front cover will slide over the front face of the base and lock into place with the mounting truss head screw. For higher horsepower drives, the cover may have hooks that clip into the drive. If so, refer to the second image below. Insert the clips into the positions shown, then slide down to lock into place and install the mounting truss head screw.



Figure 14: Installing the Front Cover (Procedure B DRN1-Bx-x)

### DRN1-C1-5 NEMA 1 Kit Install

Compatible with the following DR...C (GA800) drives: DR-240040-3C (40HP 240V drive), DR-480050-3C (50HP 480V drive)

#### **Components Supplied**

Figure 8 shows the components supplied with the DRN1-C1-5 NEMA 1 kit:



#### Figure 15: Pieces Supplied with the DRN1-C1-5 NEMA 1 Kit

- 1. Base
- 2. Front cover
- 3. Top protective cover
- 4. Conduit bracket

- 5. (2) M4 x 10mm truss head screws
- 6. (8) M4 x 10mm pan head screws
- 7. (4) M5 x 14mm pan head screws
- 8. (2) M6 x 14mm pan head screws

#### Installation

1. Remove the knock-out holes that will be used on the conduit bracket before installing. This can be done by putting the end of a flathead screwdriver into the center hole and moving up and down. Then file the rough surface to smooth the edges.



Figure 16: Removing Knock-Out Holes (DRN1-C1-5)

# DRN1-C1-5 NEMA 1 Kit Install (continued)

2. Install the top protective cover by snapping into place as shown. The arrow should point towards the front of the drive.



Figure 17: Installing the Top Cover (DRN1-C1-5)

3. Mount the base to the drive as shown below.



Figure 18: Installing the Base (DRN1-C1-5)

# DRN1-C1-5 NEMA 1 Kit Install (continued)

4. Install the conduit bracket to the base.



Figure 19: Install the Conduit Bracket (DRN1-C1-5)

5. Install the front cover.



Figure 20: Install the Front Cover (DRN1-C1-5)

## DRN1-C1-6 NEMA 1 Kit Install

Compatible with the following DR...C (GA800) drives:

DR-240050-3C (50HP 240V drive), DR-480060-3C (60HP 480V drive), DR-480075-3C (75HP 480V drive)

#### **Components Supplied**

Figure 14 shows the components supplied with the DRN1-C1-6 NEMA 1 kit:



Figure 21: Pieces Supplied with the DRN1-C1-6 NEMA 1 Kit

- 1. Base
- 2. Front cover
- 3. Top protective cover
- 4. Conduit bracket
- 5. (2) stay brackets

#### ybrackets

- 7. (16) M4 x 8mm pan head screws8. (2) M6 x 14mm pan head screws
- 9. (4) M6 x 16mm upset head bolts

6. (4) M4 x 10mm truss head screws

#### Installation

 Remove the knock-out holes that will be used on the conduit bracket before installing. This can be done by putting the end of a flathead screwdriver into the center hole and moving up and down. Then file the rough surface to smooth the edges.



Figure 22: Removing Knock-Out Holes (DRN1-C1-6)

## DRN1-C1-6 NEMA 1 Kit Install (continued)

2. Install the top protective cover by putting the hooks into the hook holes on the top of the drive and slide forward to align screw holes. Tighten screws to install.



Figure 23: Installing the Top Cover (DRN1-C1-6)

3. Install the (s) stay brackets to the drive as shown below.



A - Stay brackets B - M4 × 8 pan head screws

Figure 24: Installing the Stay Bracket (DRN1-C1-6)

# DRN1-C1-6 NEMA 1 Kit Install (continued)

4. Install the base to the stay brackets.



Figure 25: Install the Base to the Stay Brackets (DRN1-C1-6)

5. Secure the base to the drive.





# DRN1-C1-6 NEMA 1 Kit Install (continued)

6. Install the conduit bracket.



Figure 27: Install the Conduit Bracket (DRN1-C1-6)

7. Install the front cover.



Figure 28: Install the Front Cover (DRN1-C1-6)

## DRN1-C1-7/8 NEMA 1 Kit Install

Compatible with the following DR...C (GA800) drives: DR-240060-3C (60HP 240V drive), DR-240075-3C (75HP 240V drive), DR-480100-3C (100HP 480V drive), DR-480125-3C (125HP 480V drive)

#### **Components Supplied**

Figure 22 shows the components supplied with the DRN1-C1-7/8 NEMA 1 kit:



Figure 29: Pieces Supplied with the DRN1-C1-7/8 NEMA 1 Kit

- 1. Base
- 2. Front cover
- 3. Top protective cover
- 4. Conduit bracket
- 5. (2) stay brackets

- 6. (4-6) M4 x 10mm truss head screws
- 7. (16-18) M4 x 8mm pan head screws
- 8. (4) M6 x 16mm upset head bolts
- 9. (2) M8 x 16mm hex bolts
- 10. (2) M8 plain washers

#### Installation

 Remove the knock-out holes that will be used on the conduit bracket before installing. This can be done by putting the end of a flathead screwdriver into the center hole and moving up and down. Then file the rough surface to smooth the edges.



Figure 30: Removing Knock-Out Holes (DRN1-C1-7/8)

## DRN1-C1-7/8 NEMA 1 Kit Install (continued)

2. Install the top protective cover by putting the hooks into the hook holes on the top of the drive and slide forward to align screw holes. Tighten screws to install.



Figure 31: Installing the Top Cover (DRN1-C1-7/8)

3. Install the (2) stay brackets to the drive as shown below.



Figure 32: Installing the Conduit Bracket (DRN1-C1-7/8)

# DRN1-C1-7/8 NEMA 1 Kit Install (continued)

- 4. Install the base on the stay brackets.
  - DRN1-C1-7 will use 4 screws
  - DRN1-C1-8 will use 6 screws



Figure 33: Install the Base to the Drive (DRN1-C1-7/8)

5. Secure the base to the drive.



Figure 34: Securing Base (DRN1-C1-7/8)

# DRN1-C1-7/8 NEMA 1 Kit Install (continued)

6. Install the conduit bracket.



Figure 35: Install the Conduit Bracket (DRN1-C1-7/8)

- 7. Install the front cover.
  - DRN1-C1-7 will use 4 screws
  - DRN1-C1-8 will use 6 screws



Figure 36: Install the Front Cover (DRN1-C1-7/8)

## DRN1-C1-9 NEMA 1 Kit Install

Compatible with the following DR...C (GA800) drives:

DR-240100-3C (100HP 240V drive), DR-480150-3C (150HP 480V drive), DR-480200-3C (200HP 480V drive)

#### **Components Supplied**

Figure 30 shows the components supplied with the DRN1-C1-9 NEMA 1 kit:



Figure 37: Pieces Supplied with the DRN1-C1-9 NEMA 1 Kit

- 1. Base
- 2. Front cover
- 3. Top protective cover
- 4. Conduit bracket
- 5. (2) stay brackets

6. (4) M4 x 10mm truss head screws
7. (11) M4 x 10mm pan head screws
8. (16) M5 x 12mm pan head screws
9. (2) M10 x 20mm hex bolts
10. (2) M10 plain washers

#### Installation

 Remove the knock-out holes that will be used on the conduit bracket before installing. This can be done by putting the end of a flathead screwdriver into the center hole and moving up and down. Then file the rough surface to smooth the edges.



Figure 38: Removing Knock-Out Holes (DRN1-C1-9)

## DRN1-C1-9 NEMA 1 Kit Install (continued)

2. Install the top protective cover by putting the hooks into the hook holes on the top of the drive and slide forward to align screw holes. Tighten screws to install.



Figure 39: Installing the Top Cover (DRN1-C1-9)

3. Install the (2) stay brackets to the drive as shown below.



Figure 40: Installing the Stay Brackets (DRN1-C1-9)

# DRN1-C1-9 NEMA 1 Kit Install (continued)

4. Install the base to the stay brackets.



Figure 41: Install the Base to the Stay Brackets (DRN1-C1-9)

5. Secure the base to the drive.



Figure 42: Securing Base (DRN1-C1-9)

# DRN1-C1-9 NEMA 1 Kit Install (continued)

6. Install the conduit bracket.



A - Conduit bracket

B - M4 × 10 pan head screws



7. Install the front cover.



A - Front cover

B - M4  $\times$  10 truss head screws

Figure 44: Install the Front Cover (DRN1-C1-9)

### **Installing the Drive**

A template is provided with each drive to mark the location of the mounting holes. Using a level and masking tape, position the template and fasten the template to the surface where the drive will be installed. Mark the four mounting hole locations through the template with a center punch. Drill pilot holes if necessary. See below for an example of the template provided.



Figure 45: Example of a Template for Mounting



Figure 46: Drilling Pilot Holes

## Installing the Drive (continued)

For drives 10hp and under, screw the drive directly to the surface. Anchor the screws depending on the surface material. Dimensions for mounting holes can be found in technical literature DR-1000.



Figure 47: Mounting the Drive (10hp and under)

On drives over 10hp, thread screws till the heads are roughly ¼" away from the surface. Place the drive on the screws and slide the drive into the locked position. Then tighten the screws to securely mount the drive.



Figure 48: Mounting the Drive (over 10hp)

## **Fuses and Wiring**

To access the terminals on the DR-...B (GA500) drives, first remove the NEMA 1 kit cover. Next, the low voltage terminals can be accessed by sliding the tab located above the NEMA 1 kit to the unlock position. Pull down on the cover, then pull away to remove.



Figure 49: Accessing DR-...B (GA500) Wiring

To access the wiring on the DR-...C (GA800) drives, first remove the keypad by pushing down the tab on the top of the keypad and pulling the keypad forward. Next pull the keypad connector out from the drive horizontally and put it in the holder. Unscrew the screw holding the front cover and remove the wiring cover.



Figure 50: Accessing DR-...C (GA800) Wiring

See Tables 1 and 2 for a complete listing of recommended wire gauges and fuse sizes.

# Fuses and Wiring (continued)

Model	<u>Drive</u> Horsepower	R/L1, S/L2, T/L3	U/T1, V/T2, W/T3	-	+1	+2	+3	B1, B2		Incoming Power Bussmann Semiconductor Fuse	Class CC, J, or T Fuse Maximum Size (Amps)
					Single F	Phase					0.20 (
DR-240F16-1B	1/6	14 <b>(14)</b>	14 <b>(14)</b>	14 <b>(14)</b>	)		-	14 (14)	14 (14)	FWH-25A14F	2
DR-240F14-1B	1/4	14 <b>(14)</b>	14 <b>(14)</b>	14 <b>(14)</b>	)			14 (14)	14 <b>(14)</b>	FWH-25A14F	3.5
DR-240F34-1B	3/4	14 <b>(14)</b>	14 <b>(14)</b>	14 ( <b>14</b> )	)			14 (14)	14 ( <b>14</b> )	FWH-60B	9
DR-240001-1B	1	14 – 10 <b>(12)</b>	14 – 12 <b>(14)</b>	14 – 1 (12)	10 )		N/A	14 – 12 (14)	14 – 10 <b>(10)</b>	FWH-80B	15
DR-240002-1B	2	12 – 10 (10)	14 – 12 <b>(14)</b>	12 – 1 (10)	10			14 – 12 (14)	14 - 10 (10)	FWH-100B	20
DR-240003-1B	3	14 – 6 <b>(8)</b>	14 – 10 <b>(12)</b>	14 – (8)	6			14 – 12 (14)	14 – 10 <b>(10)</b>	FWH-125B	30
DR-240005-1B	5	12 – 6 <b>(8)</b>	14 – 8 <b>(10)</b>	12 – (8)	6			14 – 12 <b>(14)</b>	12 – 8 <b>(8)</b>	FWH-150B	40
	Three Phase										
DR-240F16-3B	1/6	14 <b>(14)</b>	14 <b>(14)</b>		14 <b>(14)</b>			14 (14)	14 <b>(14)</b>	FWH-25A14F	3
DR-240F14-3B	1/4	14 <b>(14)</b>	14 <b>(14)</b>		14 <b>(14)</b>			14 (14)	14 <b>(14)</b>	FWH-25A14F	3.5
DR-240F34-3B	3/4	14 <b>(14)</b>	14 <b>(14)</b>		14 <b>(14)</b>			14 (14)	14 <b>(14)</b>	FWH-25A14F	6
DR-240001-3B	1	14 <b>(14)</b>	14 <b>(14)</b>		14 <b>(14)</b>			14 (14)	14 <b>(14)</b>	FWH-25A14F	10
DR-240002-3B	2	14 – 12 <b>(14)</b>	14 – 12 <b>(14)</b>	1	14 – 10 <b>(12)</b>			14 – 12 <b>(14)</b>	14 – 10 <b>(10)</b>	FWH-70B	15
DR-240003-3B	3	14 – 12 <b>(14)</b>	14 – 12 <b>(14)</b>	1	14 – 10 <b>(12)</b>			14 – 12 <b>(14)</b>	14 – 10 <b>(10)</b>	FWH-70B	15
DR-240005-3B	5	14 – 6 <b>(8)</b>	14 – 8 <b>(10)</b>		14 – 6 <b>(8)</b>				14 – 10 (14)	14 – 8 <b>(8)</b>	FWH-90B
DR-240007-3B	7	14 – 6 <b>(8)</b>	14 – 8 <b>(10)</b>		14 – 6 <b>(8)</b>		N/A	14 - 10 (14)	14 – 8 <b>(8)</b>	FWH-90B	35
DR-240010-3B	10	12 – 6 <b>(8)</b>	12 – 6 <b>(8)</b>		12 – 6 <b>(6)</b>			12 – 8 <b>(12)</b>	10 – 6 <b>(8)</b>	FWH-100B	50
DR-240015-3B	15	12 – 6 <b>(6)</b>	12 – 6 <b>(6)</b>		10 – 2 <b>(4)</b>			14 – 6 <b>(10)</b>	10 – 6 <b>(6)</b>	FWH-150B	70
DR-240020-3B	20	10 – 2 <b>(4)</b>	10 – 2 <b>(4)</b>		8 – 2 <b>(2)</b>			12 – 6 <b>(8)</b>	8 – 4 (6)	FWH-200B	90
DR-240025-3B	25	6 – 1 (2)	8 – 1 (2)	6	6 – 1/0 (1)			12 – 6 <b>(8)</b>	6 – 4 <b>(4)</b>	FWH-200B	110
DR-240030-3B	30	6 – 1/0 (1)	6 – 1 (2)	2	2 – 2/0 <b>(2/0)</b>			10 – 6 <b>(6)</b>	6 – 4 <b>(4)</b>	FWH-225A	125
DR-240040-3C	40	6 – 1/0 (1/0)	6 – 1/0 (1/0)	2 – 2/ <b>(2/0</b>	/0 I)			10 – 4 (4)	6 – 4 (6)	FWH-225A or FWH-250A	175
DR-240050-3C	50	2 – 2/0 <b>(2/0)</b>	2 – 2/0 <b>(2/0)</b>	2 – 4/ <b>(4/0</b>	/0 )			10 – 3 <b>(3)</b>	4 (4)	FWH-275A or FWH-300A	225
DR-240060-3C	60	2/0 – 250 <b>(4/0)</b>	3/0 – 300 <b>(4/0)</b>	1/0 – 2 (1)	2/0	N/A	1 – 2/0 (1/0)		4 -1/0 (4)	FWH-275A or FWH-300A	250
DR-240075-3C	75	2/0 – 250 <b>(250)</b>	3/0 – 300 <b>(300)</b>	1/0 – 2 <b>(2/0</b>	2/0 I)		1 – 2/0 (2/0)	N/A	4 -1/0 (4)	FWH-325A or FWH-450A	350
DR-240100-3C	100	2/0 – 4/0 x 2P (2/0 x 2P)	2/0 – 4/0 x 2P (2/0 x 2P)	4/0 – 250 <b>(4/0 x</b> )	0 x 2P <b>2P)</b>		1/0 x 2P <b>(1/0 x 2P)</b>		3 – 350 <b>(3)</b>	FWH-600A	400

#### Table 1: Suggested Wire Gauge and Fuses for DR-240... (Single and Three Phase 240V Drives)

Note: Recommended wire gauge shown in parentheses.

# Fuses and Wiring (continued)

	Drive	P/11 S/12	11/T1 \//T2							Incoming Power	Class CC, J,
Model	Horsepower	T/13	W/T3	- +1	+2	+3	B1, B2	$(\bot)$	Semiconductor	Maximum	
	<u></u>	.,=0	,						$\overline{}$	Fuse	Size (Amps)
		l		T	hree Pha	se					
		14 - 12	14 - 12	1	14 - 12			14 - 12	14 - 10		
DR-480F12-3B	1/2	(14)	(14)		(14)			(14)	(14)	FWH-40B	3
	-	14 - 12	14 - 12		14 - 12			14 - 12	14 - 10		
DR-480001-3B	1	(14)	(14)		(14)			(14)	(14)	FWH-40B	3.5
DD 400003 3D	2	14 - 12	14 - 12		14 - 12	1		14 - 12	14 - 10		7
DK-480002-35	2	(14)	(14)		(14)			(14)	(10)	FWH-SUB	,
DR-480003-3B	3	14 - 12	14 - 12		14 - 12	2		14 - 12	14 - 10	EW/H-70B	9
511 400000 55	,	(14)	(14)		(14)			(14)	(10)	1111705	5
DR-480005-3B	5	14 - 12	14 - 12		14 - 12	1		14 – 12	14 - 10	FWH-70B	15
	-	(14)	(14)		(14)			(14)	(10)		
DR-480007-3B	7	14 - 10	14 – 12		12 – 8			14 – 12	14 - 10	FWH-90B	20
		(12)	(14)		(10)			(14)	(10)		
DR-480010-3B	10	12-8	12 - 8		14 - 8			14 - 12	14 - 6	FWH-80B	30
		(10)	(10)		12 6		(14)		(10)		
DR-480015-3B 15	15	15 (8)	(10)	(8)			N/A	(12)	(10)	FWH-100B	40
		12 - 6	12 - 6		12 - 4		-	12 - 8	10 - 6		
DR-480020-3B	20	(8)	(8)		(6)			(10)	(8)	FWH-125B	50
		12 - 6	12 - 6		10 - 2			14 - 6	10 - 6		
DR-480025-3B	25	(8)	(8)		(4)			(10)	(6)	FWH-175B	60
DR 480030 38	20	10 - 2	12 - 4		8 - 2			12 - 6	10 - 6	EW/11 2000	70
DR-480030-3B	30	(4)	(6)		(2)			(8)	(6)	FWH-200B	70
DR-480040-3B	40	8 - 2	10 - 2		6 - 2			12 - 6	10 - 6	FW/H-200B	100
DI(-400040-3D	40	(2)	(4)		(2)			(8)	(6)	1 WH 2005	100
DR-480050-3C	50	10 - 2	10 - 2	10 -	- 2			14 – 6	6 - 4	FWH-250A	125
		(2)	(2)	(2	)			(6)	(6)		-
DR-480060-3C	60	10 - 2	10 - 2	6-1	1/0			14 – 6	6 - 4	FWH-250A or	150
		(2)	(2)	(1/	0)			(6)	(4)	FWH-275A	
DR-480075-3C	75	2 - 2/0	2 - 2/0 (1)	2-4	4/U			10-3	6-4	FWH-250A Or	175
		2/0 - 250	3/0 - 300	1/0-	2/0		1/0 - 2/0	(3)	(4)	FWH-275A	
DR-480100-3C	100	(3/0)	(2/0)	1/0-	)	N/A	(2)		(4)	FWH-300A	225
		2/0 - 250	3/0 - 300	1/0-	2/0		$\frac{1}{0} - \frac{2}{0}$		4 - 1/0	FWH-325A or	
DR-480125-3C	125	(4/0)	(4/0)	(1/	0)		(1/0)		(4)	FWH-400A	250
		2/0 – 4/0 x 2P	2/0 – 4/0 x 2P	4/0 - 25	50 x 2P		1/0 x 2P	N/A	4 -350		
DR-480150-3C	150	(1/0 x 2P)	(1/0 x 2P)	(3/0)	( 2P)		(1/0 x 2P)		(4)	FWH-500A	350
DR 480300 30	200	2/0 – 4/0 x 2P	2/0 – 4/0 x 2P	4/0-25	50 x 2P		1/0 x 2P		2 - 350		400
DK-480200-3C	200	(2/0 x 2P)	(2/0 x 2P)	(3/0)	( 2P)		(1/0 x 2P)		(2)	FWH-600A	400

#### Table 2: Suggested Wire Gauge and Fuses for DR-480... (480V Three Phase Drives)

Note: Recommended wire gauge shown in parentheses.

## Fuses and Wiring (continued)

Install the motor wiring and power wiring. For three phase power input use terminals R/L1, S/L2, and T/L3. For single phase power input use L/L1 and N/L2 (not shown in figure 51).



Figure 51: Example Main Circuit and Motor Connections

#### Main Circuit and Motor Connection Notes:

- If the motor turns the wrong direction, swap any two output wires such as U/T1 and V/T2 and the motor will turn the opposite direction.
- If input power is applied to T1, T2, and T3 severe drive damage will occur.

# LMV52 Wiring

Note: A speed sensor must be installed on the motor to use a LMV52. Please see installation instructions LMV-3050 for more details on mounting an AGG5.305 speed sensor kit.



Figure 52: LMV52 Wiring to DR-...B (GA500) OR DR-...C (GA800) Drives

## LMV52 Wiring (continued)

LMV52 Wiring Notes:

- If using a GA800/DR-...C the jumper must be installed as shown in Figure 52
- The thermal switch wiring and Run/Stop dry contact will go to SC (for GA500/DR-...B) or SN (for GA800/DR-...C)
- Check the resistances between the ground terminals on the LMV5, drive, and the motor. Resistance must not exceed 20 ohms
- 4-20mA wiring and speed sensor cabling must be shielded cable
- Line reactors, load reactors, and braking resistors are optional. Refer to the Drive Technical Instructions (DR-1000) for more information.
- If only using single phase input power, do not wire L3
- See page 38 if using a braking unit with the braking resistor

## LMV3 Wiring

Note: Most LMV3 applications require a speed sensor installed. Please see installation instructions LMV-3050 for more details on mounting an AGG5.305 speed sensor kit.



Figure 53: LMV3 Wiring to DR-...B (GA500) OR DR-...C (GA800) Drives

## LMV3 Wiring (continued)

LMV3 Wiring Notes:

- If using a GA800/DR-...C the jumper must be installed as shown in Figure 53
- The thermal switch wiring and Run/Stop dry contact will go to SC (for GA500/DR-...B) or SN (for GA800/DR-...C)
- Check the resistances between the ground terminals on the LMV3, drive, and the motor. Resistance must not exceed 20 ohms
- 4-20mA wiring and speed sensor cabling must be shielded cable
- Line reactors, load reactors, and braking resistors are optional. Refer to the Drive Technical Instructions DR-1000 for more information.
- If only using single phase input power, do not wire L3
- See page 38 if using a braking unit with the braking resistor

# Terminals



Figure 54: Main Circuit and Motor Terminals

Terminal	Description		<b>_</b>		
	Single Phase	Three Phase	Function		
R/L1					
S/L2	-	Power Supply			
T/L3			Incoming Power Supply Connection		
L/L1	Dowor Supply				
N/L2	Power Supply	-			
U/T1					
V/T2	Drive	Output	Motor Connection		
W/T3					
B1	Proking Posi	stor Connection	Proking Posistor Connection		
B2	DI AKII ING KESIS		Braking Resistor Connection		
+3		ly Input (11 and )	Deripheral Device Connections (DC Dewer		
+2	DC Power Supp	ny input (+1 and -)	Peripheral Device Connections (DC Power		
+1	DC Reactor Connection (+1 and +2)		removing jumper between (1 and (2)		
-	Braking Unit Connection (+3 and -)		removing jumper between +1 and +2)		
Cround	Gr	ound	240V: D Class Ground to 100 Ohms or less		
Ground	Gr	ounu	480V: C Class Ground to 10 Ohms or less		

<b>Table 3: Main Circuit and Motor Connection</b>	ons
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# **Terminals (continued)**



#### Figure 55: Multi-Function Input Terminals

Table 4:	Commonly	Used	Input	Terminals
----------	----------	------	-------	-----------

Terminal	Description	Function		
SP		Input Power Supply +24VDC		
SN		Neutral		
SC	Drive Inputs	Selection Common		
S1		Forward Run Command		
S3		External Fault: N/O		
AC		Common		
A1 Master Frequency Reference		Frequency Reference 1		
		Frequency Reference 2		

## **Dip Switches**

Note: Dip switches will be correct at default positions. All the dip switches are listed here for verification purposes.



Position	Switch	Terminal	Function	Default
А	Jumper switch S5	AM	Sets the output method for terminal AM (voltage or current).	V (voltage output)
	DIP switch S1 A2		Sets the input method for terminal A2 (voltage or current).	I (current input)
В	DIP switch S2	-	Enables and disables the MEMOBUS/Modbus communications termination resistor.	OFF

Figure 56: DR...B (GA500) Dip Switches



Position	Switch	Terminal	Function	Default
А	DIP switch S2	-	Enables and disables the MEMOBUS/Modbus communications termination resistor.	OFF
В	Jumper switch S5	FM, AM	Sets terminals FM and AM to voltage or current output.	FM: V (voltage output) AM: V (voltage output)
	DIP switch S1-1	A1	Sets the input signal type (voltage/current).	V (voltage input)
С	DIP switch S1-2	A2	Sets the input signal type (voltage/current).	I (current input)
	DIP switch S1-3	A3	Sets the input signal type (voltage/current).	V (voltage input)
D	DIP switch S4	A3	Sets MFAI or PTC input.	AI (analog input)

Figure 57: DR	C (GA800)	<b>Dip Switches</b>
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#### Parameters

Note: All drives will come preprogrammed for each application. All parameters below are for setting the LMV52/LMV3 to work seamlessly with the drive.

Note: LO/REM button should be in REM mode to accept the LMV5/LMV3 signal.

#### LMV52:

The following parameters MUST be set in the LMV52:

- a. OperatRampMod = 30 seconds or greater
- b. TimeNoFlame = 30 seconds or greater
- c. ReleaseContactVSD = Open
- d. Setpoint Output = 4-20mA
- e. Settling Time = 16

The LMV52 / drive / blower must also be standardized after installation and wiring are complete. This is accomplished by setting the following parameters in the LMV52:

- a. VSD = activated or air influenced
- b. Air Actuator = air influenced
- c. Standardization = activated

After "standardization" is set to activated, the air damper should open to the pre-purge position and the blower should ramp up to maximum speed. See LMV52 Technical Instructions (LV5-1000) for more details.

NOTE: The LMV52 will not standardize if the safety loop is open.

#### LMV3:

The following parameters MUST be set in the LMV3:

- a. 522 (VSD ramp up time) = 20 seconds or greater
- b. 523 (VSD ramp down time) = 20 seconds or greater
- c. 542 (activation of VSD) = 1 (activated)
- d. 645 (configuration of analog output) = 0 (0 to 10 VDC)

When a speed sensor is installed, a LMV3 / drive / blower must also be standardized after installation and wiring are complete. This is accomplished by setting the following parameters in the LMV3:

641 (activate VSD standardization) = 1 (activated). After "standardization" is set to activated, the air damper should open to the pre-purge position and the blower should ramp up to maximum speed. See LMV3 Technical Instructions (LV3-1000) for more details.

## **Braking Units**

Drives listed in table 5 require braking units when using a braking resistor.

Voltage Class	Drive Part Number	Drive Horsepower
	DR-240060-3C	60
200V	DR-240075-3C	75
	DR-240100-3C	100
400V	DR-480150-3C	150
	DR-480200-3C	200

#### **Table 5: Drives Requiring Braking Units**

For mounting, install the braking unit upright with sufficient space around it for air flow and wiring. Once mounted, the Voltage Rotary Switch must be set to your field voltage. See figure 59 and table 6 for more information.



- A Braking Activation Voltage Rotary Switch S3
- B Master/Slave Selection DIP Switch S2
- C Control Circuit Terminals (TB2)
- D Main Circuit Terminals (B1, B2)
- E Grounding Terminal

- F + and Main Circuit Terminals (TB3)
- G Control Circuit Terminals (TB1)
- H Fault Relay Enable/Disable DIP Switch S5 Note: Available in Rev. B and later.
- I N.O./N.C. DIP Switch S4
- J Sink/Source DIP Switch S1



# Braking Units (continued)



Figure 59: Voltage Rotary Switch Location

	200 V	Class	400 V Class		
Setting	Input Voltage (V)	Braking Activation Voltage (V) (PN Bus Voltage)	Input Voltage (V)	Braking Activation Voltage (V) (PN Bus Voltage)	
0	160	270 (TYP)	380	630 (TYP)	
1	170	282 (TYP)	390	644 (TYP)	
2	175	294 (TYP)	400	659 (TYP)	
3	185	307 (TYP)	405	673 (TYP)	
4	190	319 (TYP)	415	688 (TYP)	
5	200	331 (TYP)	425	702 (TYP)	
6	208	343 (TYP)	430	717 (TYP)	
7	215	356 (TYP)	440	731 (TYP)	
8	220	368 (TYP)	450	746 (TYP)	
9 <1>	230	380 (TYP)	460	760 (TYP)	

#### **Table 6: Voltage Rotary Switch Settings**

<1> = Default Setting

# **Braking Units (continued)**





# Appendix A: Navigating the Parameters Using the Keypad



Figure 61: DR...B (GA500) Parameter Paths

# Appendix A: Navigating the Parameters Using the Keypad (continued)

A: Initialization		d: Reference Settings		H: Te	H: Terminal Functions		pecial Adjustment	9	q: DriveWorksEZ Parameters		
A1	Initialization	d1	Frequency Reference	H1	Digital Inputs	n1	Hunting Prevention	r	r: DriveWorksEZ Connections		
A2	User Parameters	d2	Reference Limits	H2	Digital Outputs	n2	Auto Freq. Regulator (AFR)	Т	T: Motor Tuning		
b: Application		d3	Jump Frequency	H3	Analog Inputs	n3	High Slip/Overexcite Braking	][	T0 Tuning Mode Selection		
b1	Operation Mode Selection	d4	Freq. Ref. Up/Down & Hold	H4	Analog Outputs	n5	Feed Forward Control	][7	1 Induction Motor Auto-Tuning		
b2	DC Injection Braking and Short Circuit Braking	d6	Field Weakening/Forcing	H5	Modbus Communication	n6	Online Tuning		PM Motor Auto-Tuning		
b3	Speed Search	d7	Offset Frequency	H6	Pulse Train Input/Output	n7	EZ Drive	][]	T3 ASR and Inertia Tuning		
b4	Timer Function	E: M	otor	H7	Virtual Inputs/Outputs	n8 PM Motor Control Tuning		][	F4 EZ Tuning		
b5	PID Control	E1	V/f Pattern for Motor 1	L: Pr	otection Functions	nA PM Motor Control Tuning		U: Monitors			
b6	Dwell Function	E2	Motor 1 Parameters	L1	Motor Protection	o: Keypad-Related Settings		][ī	J1 Operation Status Monitors		
b8	Energy Saving	E3	V/f Pattern for Motor 2	L2	Power Loss Ride Through	01	Keypad Display	16	J2 Fault Trace		
C: Ti	ining	E4	Motor 2 Parameters	L3	Stall Prevention	o2	Keypad Operation	16	J3 Fault History		
C1	Accel & Decel Time	E5	PM Motor Settings	L4	Speed Detection	o3	Copy Keypad Function	1	J4 Maintenance Monitors		
C2	S-Curve Characteristics	E9	Motor Setting	L5	Fault Restart	o4	Maintenance Monitors	][	J5 PID Monitors		
C3	Slip Compensation	F: Options		L6	Torque Detection	o5	Log Function	][	J6 Operation Status Monitors		
C4	Torque Compensation	F1	PG Speed Control Fault Detection	L7	Torque Limit			Γ	J8 DriveWorksEZ Monitors		
C5	Auto Speed Regulator (CSR)	F6	Communication Option	L8	Drive Protection						
C6	Duty & Carrier Frequency	F7	Ethernet Options								

Figure 62: DR...B (GA500) Parameter Groups

## Appendix A: Navigating the Parameters Using the Keypad (continued)



Figure 63: DR...C (GA800) Parameter Paths

A: Initialization		d: Poference Settings		H: Terminal Eurotions		n: Special Adjustment			a: DriveWorkeE7 Decemptore		
A. Initialization		u. Reference Settings		n. Terminal Functions				48	q. Driveworksez Parameters		
A1	Initialization	ď	Frequency Reference	H1	Digital Inputs	n1	Hunting Prevention	Ш	r: DriveWorksEZ Connections		
A2 User Parameters		d	Reference Limits	H2	Digital Outputs	n2	Auto Freq. Regulator (AFR)		T: Motor Tuning		
b: Application		d	Jump Frequency	H3	Analog Inputs	n3	High Slip/Overexcite Braking		U: Monitors		
b1	Operation Mode Selection	d	Freq. Ref. Up/Down & Hold	H4	Analog Outputs	n4	AOLV Tuning	1[	U1	Operation Status Monitors	
b2	DC Injection Braking and Short Circuit Braking	d	Torque Control	Н5	Modbus Communication	n5	Feed Forward Control		U2	Fault Trace	
b3	Speed Search	d	Field Weakening/Forcing	H6	Pulse Train Input/Output	n6	Online Tuning		U3	Fault History	
b4	Timer Function	ď	Offset Frequency	H7	Virtual Inputs/Outputs	n7	EZ Drive	][	U4	Maintenance Monitors	
b5	PID Control	E:	Motor	L: Protection Functions		n8	PM Motor Control Tuning		U5	PID Monitors	
b6	Dwell Function	E	V/f Pattern for Motor 1	L1	Motor Protection	o: Ke	eypad-Related Settings	1	U6	Operation Status Monitors	
b7	Droop Control	E:	Motor 1 Parameters	L2	Power Loss Ride Through	01	Keypad Display		U8	DriveWorksEZ Monitors	
b8	Energy Saving	E	V/f Pattern for Motor 2	L3	Stall Prevention	o2	Keypad Operation				
b9	Zero Servo	E	Motor 2 Parameters	L4	Speed Detection	03	Copy Keypad Function				
C: Tuning		E	PM Motor Settings	L5	Fault Restart	o4	Maintenance Monitors				
C1	Accel & Decel Time	E	Motor Setting	L6	Torque Detection	o5	Log Function				
C2	S-Curve Characteristics	F:	F: Options		Torque Limit			_			
C3	Slip Compensation	F	PG Option Setup (Encoder)	L8	Drive Protection						
C4	Torque Compensation	E	Analog Input Option	L9	Drive Protection 2						
C5	Auto Speed Regulator (CSR)	F	Digital Input Option								
C6	Duty & Carrier Frequency	F4	Analog Output Option								
		F	Digital Output Option								
		F	Communication Option								
		F	Ethernet Options								

Figure 64: DR...C (GA800) Parameter Groups



# Appendix B: DR...B (GA500) Control Circuit Wiring

Figure 65: DR...B (GA500) Control Circuit

# Appendix C: DR...C (GA800) Control Circuit Wiring



Figure 66: DR...C (GA800) Control Circuit

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